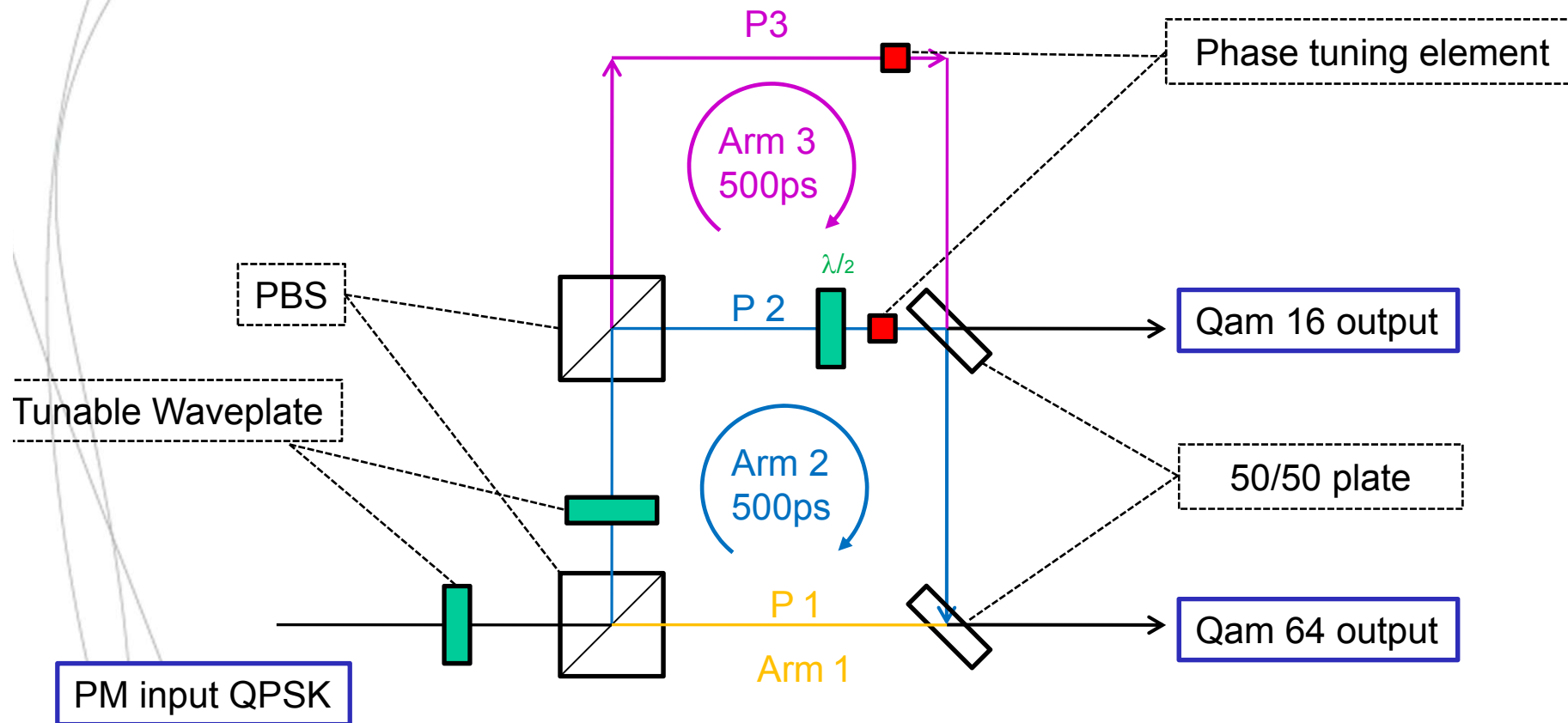


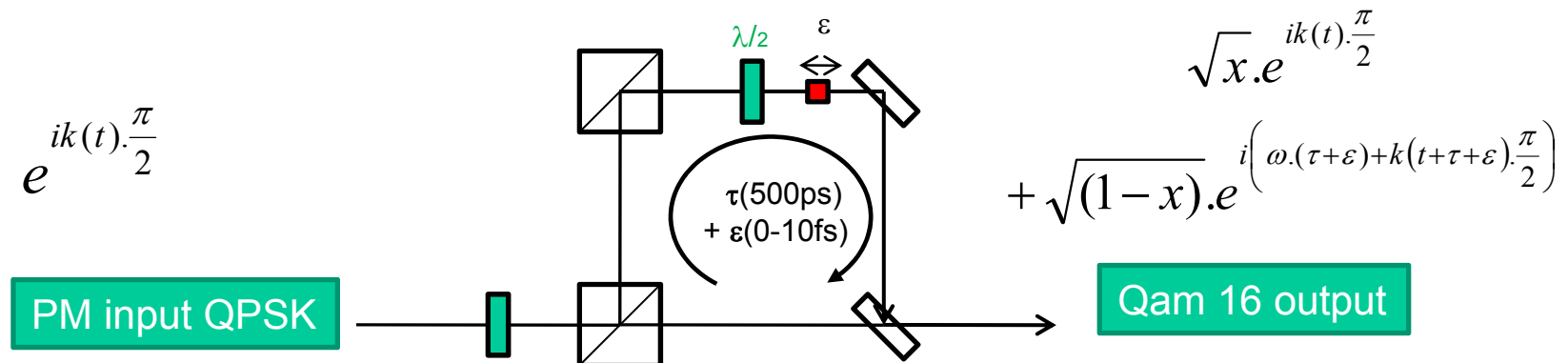
Quadrature Amplitude Emulator : QAME

Principle drawing



Principle mathematics (case QAM16) kULia

- Case QAM 16

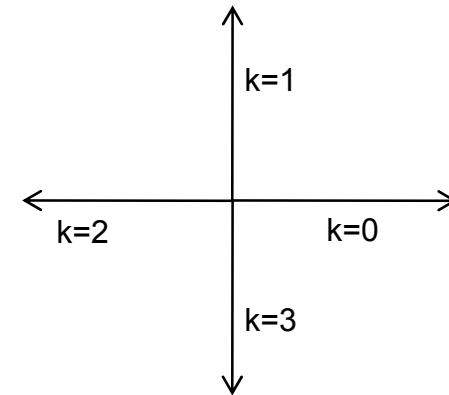


- Input $e^{ik(t) \cdot \frac{\pi}{2}}$
 - » Where **k(t) is an integer** that changes every T seconds.
 - T=1/F where F is the modulation frequency (typ T= 40 GHz, and k is [0,1,2,3] (QPSK signal))

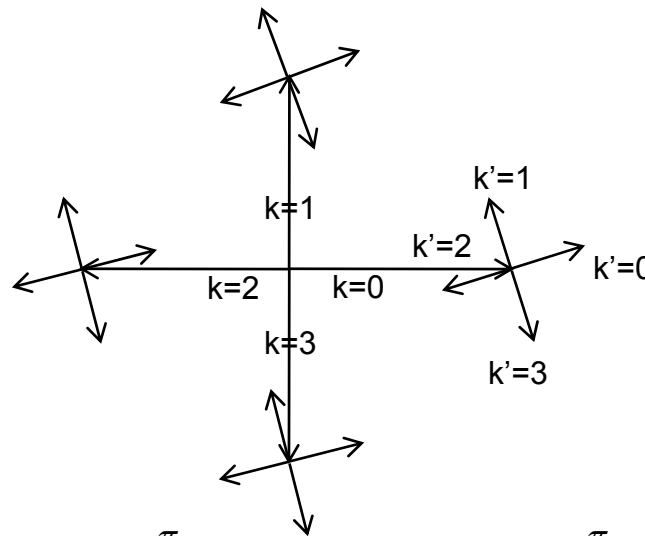
- Output $\sqrt{x}.e^{ik(t).\frac{\pi}{2}} + \sqrt{(1-x)}.e^{i\left(\omega.(\tau+\varepsilon)+k(t+\tau+\varepsilon).\frac{\pi}{2}\right)}$
 - **x** is the splitting ratio,
 - $\omega=2\pi.f$, where **f** is the **optical frequency** (e.g 193.400 THz),
 - τ is the delay introduced by the interferometer. **$\tau=500\text{ps}$** ,
 - ε is the additionnal delay introduced by the **phase tuning element**.
 $0 < \varepsilon < 10\text{fs}$, and so does not change the value of $k(t+\tau)$, but **enables $\omega.(\tau+\varepsilon)$ to be a multiple of 2π** .
- **The value of 500ps** enables the device to work with **modulation frequencies that are even and integer** in GHz (e.g $f=10, 12, \dots, 24, 26, \dots, 38, 40$ etc.) Then we have
 - › A delay of 5 symbols @10GHz ,
 - › 10 symbols@20 GHz
- We can note **$k'(t)=k(t+\tau)$** for simplifying.

constellation

- If we represent the electric field in amplitude and phase we have:



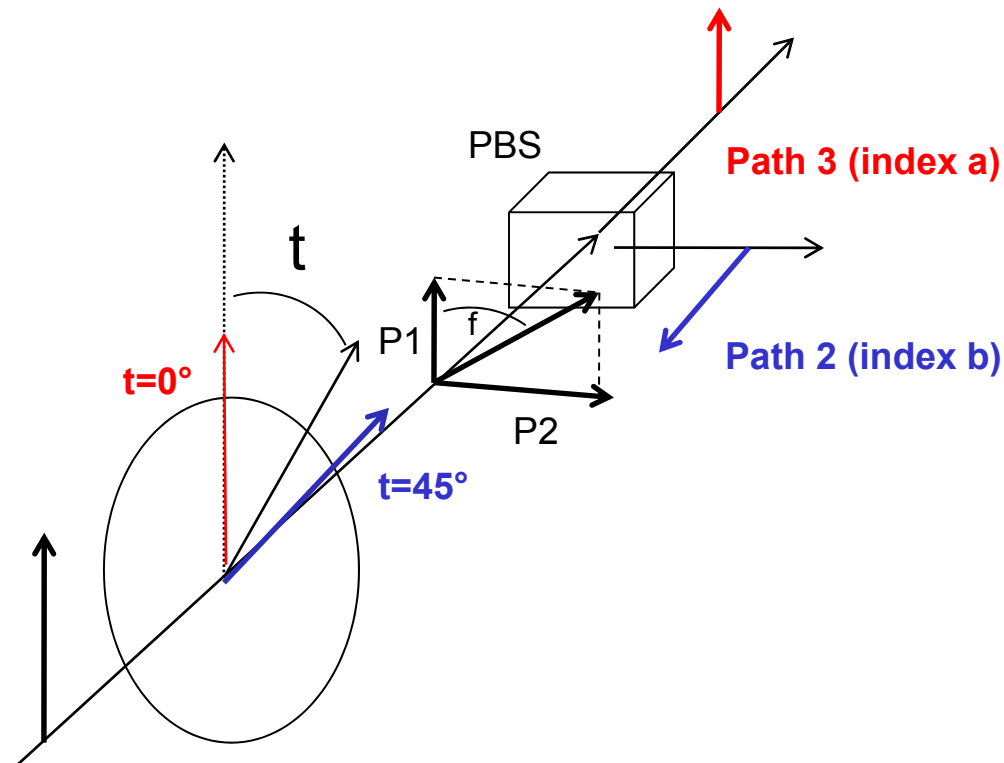
$$e^{i.k(t).\frac{\pi}{2}}$$



$$\sqrt{x}.e^{i.k(t).\frac{\pi}{2}} + \sqrt{(1-x)}.e^{i.k'(t).\frac{\pi}{2}}$$

How to adjust power splitter? (case QAM16)

- Tunable coupler is based on a phase plate tunable between 0° and 45°
 - » When $t=0^\circ$ (all power on Path3: index a) $\rightarrow i=a$
 - » to 45° (all power on Path2: index b). $\rightarrow i=b$
 - » The index i indicates the phase plate angle t .



$$t = 45 \times \frac{(i - a)}{(b - a)}$$

$$i = \frac{t \times (b - a)}{45} + a$$

- The angle of the polarization f is the double of the angle of the phase plate

$$f=2t$$

- The ratio of the power between arm2 (P_2) and arm3 (P_3)

$$P_2/P_3=(\tan(f))^2$$

- If relative power on arm 2 is $P_2= x$ then power on arm3 is $P_3=1-x$.

- $\tan(2.t)=\tan(f)=\sqrt{x/(1-x)},$

$$i = \frac{1}{2} \times \arctan\left(\sqrt{\frac{x}{1-x}}\right) \times \frac{(b-a)}{45} + a$$

- Example $P_2=2.P_3$ (or $x=1/3$) ,

$$a=100$$

$$b=1688$$

$$\text{then } f=54.7^\circ, t=27.4^\circ \text{ and } i=1066$$

Features



- Good 90° stability
- Low excess IL ($< 3\text{dB}$)
- Complete 3-path power balancing
- Options available
 - » Fixed ratio component (factory settings of debalancement and no tunable element)
 - » Shutter on one arm

Applications



- QAM16 emulation
- QAM64 emulation
- QPSK emulation

Related products



- Coherent receiver (COH24 & COH28)
- PDM emulator (PDME)
- Polarizer
- Variable Optical Delay Line (VODL)

